

Tracking Vector Magnetic Fields

HMI Science Team Meeting
September 8-11, 2009, Stanford, CA
Supported by NASA: NNH06AD87I

P. W. Schuck
Peter.Schuck@nasa.gov

Room 236, Building 21
Space Weather Laboratory, Code 674
Heliospheric Science Division
Goddard Space Flight Center
Greenbelt, MD 20771

Collaborators:
Jacob Hageman (GSFC)
Brian Welsch, George Fisher, and Bill Abbett (SSL/Berkeley)

- Incorporate plasma physics into solar motion estimation: Analyze vector magnetograms with ideal MHD
- Determine 3D photospheric plasma velocities
- Test CME initiation models that require neutral line footpoint shearing
- Quantify the magnitude and timing of energy and helicity fluxes in active regions
- Provide boundary conditions for MHD simulations of the corona

Caveat Emptor!

- The velocities estimated from optical flow techniques *depend* on motion model applied
 - **All** velocity estimation algorithms have an underlying motion model
 - Even Local Correlation Tracking (LCT) has an assumed motion model: advection in a uniform flow.
- If the images do not satisfy the motion model, the methods will produce (at best) biased results due to model misspecification.
 - The results may not be simply related to local plasma velocities and the onus is on the user to “interpret” these estimates.
 - These “velocities” may be *still* be useful for empirical image processing, i.e., image segmentation.

- Local Correlation Tracking (for small displacements)

$$C \approx \int d^2x \overbrace{w(\boldsymbol{\chi} - \mathbf{x})}^{\text{Aperture}} \left[\overbrace{\partial_t I_n(\mathbf{x}, t) + \hat{\mathbf{u}}_0 \cdot \nabla I_n(\mathbf{x}, t)}^{\text{Advection Equation}} \right]^2$$

- Differential Affine Velocity Estimator (DAVE)

$$C \approx \int d^2x w(\boldsymbol{\chi} - \mathbf{x}) \left\{ \partial_t n(\mathbf{x}, t) + \nabla \cdot \left[n(\mathbf{x}, t) \left(\hat{\mathbf{u}}_0 + \widehat{\mathbf{W}} \cdot \mathbf{x} \right) \right] \right\}^2$$

$$C \approx \int d^2x w(\boldsymbol{\chi} - \mathbf{x}) \left\{ \partial_t n(\mathbf{x}, t) + \left(\hat{\mathbf{u}}_0 + \widehat{\mathbf{W}} \cdot \mathbf{x} \right) \cdot \nabla n(\mathbf{x}, t) \right\}^2$$

Track the vertical component of \mathbf{B} to produce biased estimates of the horizontal plasma velocities (see *Caveat Emptor*).

Optical Flow Models

- Differential Affine Velocity Estimator for Vector Magnetograms (DAVE4VM)

$$C \approx \int dx^2 w(\mathbf{x} - \chi) \left\{ \partial_t B_z(\mathbf{x}, t) + \nabla_h \cdot [B_z(\mathbf{x}, t) \hat{\mathbf{v}}_h - \hat{\mathbf{v}}_z \mathbf{B}_h(\mathbf{x}, t)] \right\}^2$$

$$\hat{\mathbf{v}} = \begin{pmatrix} u_0 \\ v_0 \\ w_0 \end{pmatrix} + \begin{pmatrix} \hat{u}_x & \hat{u}_y \\ \hat{v}_x & \hat{v}_y \\ \hat{w}_x & \hat{w}_y \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad \nabla_h = (\partial_x, \partial_y)$$

- Incorporates both vertical and horizontal magnetic field components
- 3D photospheric plasma velocities: explicit vertical flows
- Variational principle results in a least squares/total least squares estimator
 - Can incorporate magnetic field covariance matrices (uncertainties)
- Pretty fast and efficient: 30 seconds for a 288×288 image (in IDL) and should be faster in parallel Fortran

Main Difference(s) Between DAVE & DAVE4VM

- DAVE implements the Démoulin & Berger (2003) assumption that tracking the vertical component of \mathbf{B} is equivalent to tracking the footpoint velocity (or flux transport velocity) \mathbf{u}

$$\partial_t B_z + \nabla_h \cdot (\mathbf{u} B_z) = 0 \qquad \mathbf{u} B_z \implies \mathbf{v}_h B_z - v_z \mathbf{B}_h$$

- DAVE4VM independently estimates the horizontal and vertical plasma velocities (and shears) and computes the footpoint velocity from these

$$\partial_t B_z + \nabla_h \cdot (\mathbf{v}_h B_z - v_z \mathbf{B}_h) = 0 \qquad \mathbf{v}_h B_z - v_z \mathbf{B}_h \implies \mathbf{u} B_z$$

- Démoulin & Berger assumption equivalent to $\mathbf{B}_h = 0$. Results in biased estimates of the horizontal plasma velocity \mathbf{v}_h ... not the footpoint velocity \mathbf{u} .

Main Difference(s) Between DAVE & DAVE4VM

- DAVE implements the Démoulin & Berger (2003) assumption that tracking the vertical component of \mathbf{B} is equivalent to tracking the footpoint velocity (or flux transport velocity) \mathbf{u}

$$\partial_t B_z + \nabla_h \cdot (\mathbf{u} B_z) = 0 \qquad \mathbf{u} B_z \implies \mathbf{v}_h B_z - v_z \mathbf{B}_h$$

- DAVE4VM independently estimates the horizontal and vertical plasma velocities (and shears) and computes the footpoint velocity from these

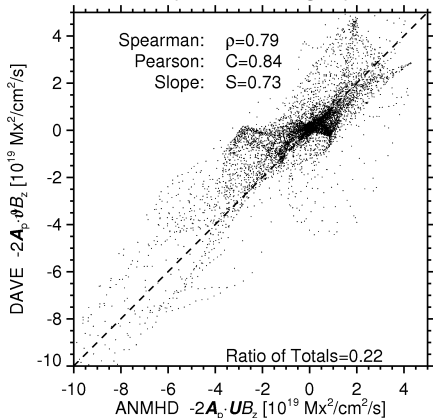
$$\partial_t B_z + \nabla_h \cdot (\mathbf{v}_h B_z - v_z \mathbf{B}_h) = 0 \qquad \mathbf{v}_h B_z - v_z \mathbf{B}_h \implies \mathbf{u} B_z$$

- Démoulin & Berger assumption equivalent to $\mathbf{B}_h = 0$. Results in biased estimates of the horizontal plasma velocity \mathbf{v}_h ... not the footpoint velocity \mathbf{u} .

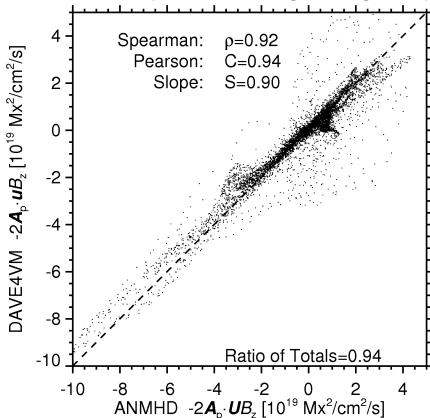
Verification against ANMHD simulations

Helicity and Energy Fluxes

DAVE (Line-of-Sight)



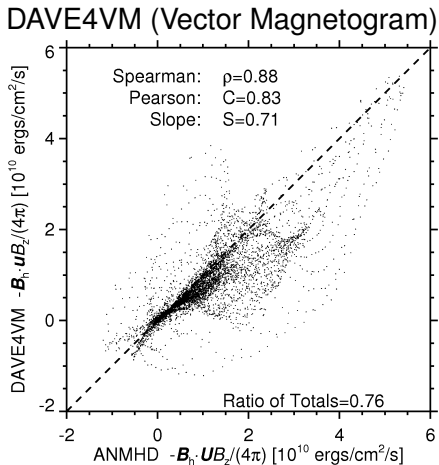
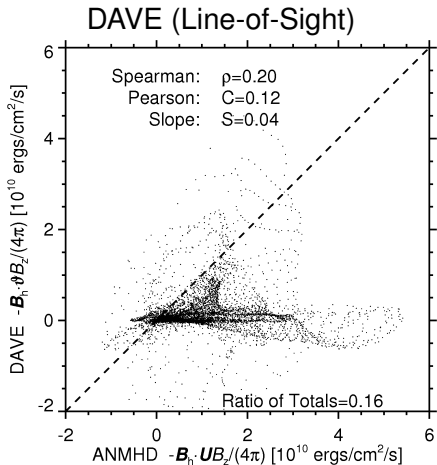
DAVE4VM (Vector Magnetogram)



- Constrain the timing and magnitude of Helicity flux

Verification against ANMHD simulations

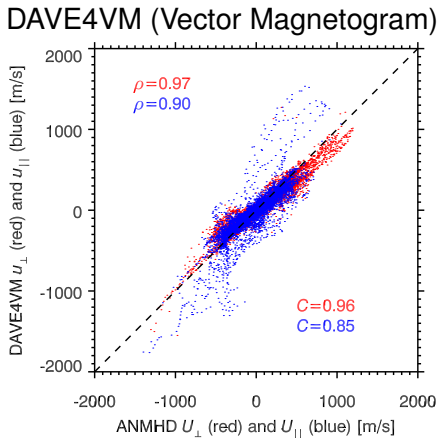
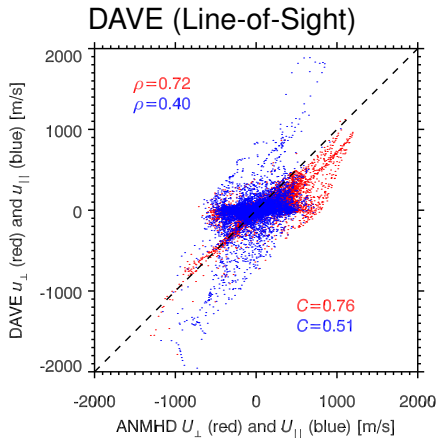
Helicity and Energy Fluxes



- Constrain the timing and magnitude of Poynting flux

Verification against ANMHD simulations

DAVE4VM Can Estimate Neutral-Line Shear Flows!

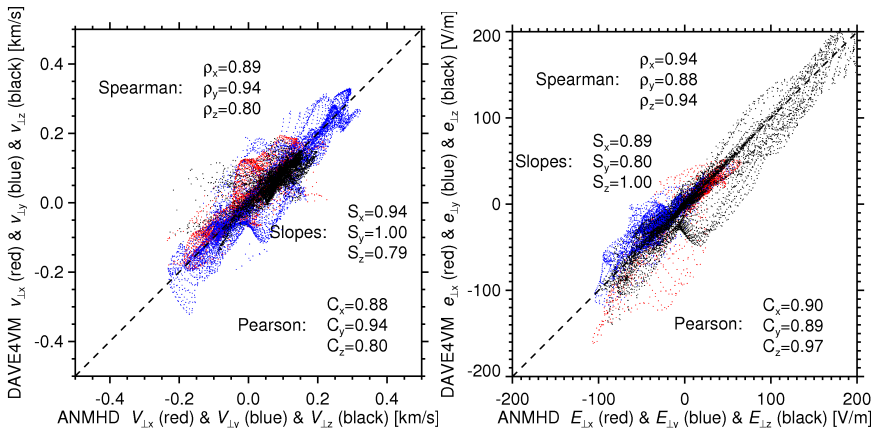


\perp and \parallel measured relative to contours of B_z

- Constrain CME initiation models

Verification against ANMHD simulations

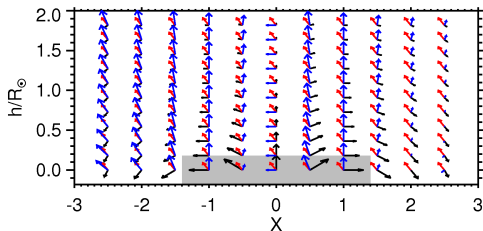
Data products for theory programs



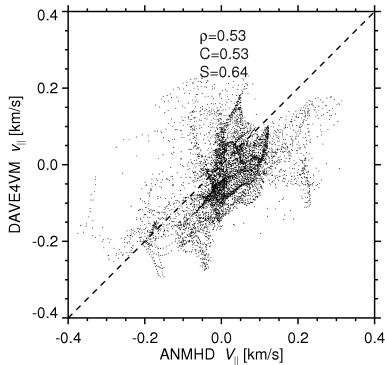
- Boundary conditions (\mathbf{E} or \mathbf{v}) for simulations CME initiation.

Verification against ANMHD simulations

DAVE4VM Can Estimate Field Aligned Flows!



Schematic diagram of a uniform plasma flow across a diverging magnetic field above the photosphere at $h = 0$. The black arrows indicate the strength and direction of the magnetic field, the red arrows indicate the direction of the spatially uniform total plasma velocity \mathbf{v} , and the blue arrows indicate the magnitude and direction of the perpendicular plasma velocity \mathbf{v}_\perp . The aperture in the photosphere is indicated by the gray box.



(Schuck, 2008)

- IDL Codes: DAVE/DAVE4VM released with ancillary routines and examples/figures from article (Schuck, *ApJ*, **683**, 1134-1152, 2008)
 - Oldest: Archived with ApJ
www.iop.org/EJ/abstract/0004-637X/683/2/1134
 - More Recent: Archived at NRL
wwwppd.nrl.navy.mil/whatsnew/dave/index.html
 - Latest: contact me at NASA – peter.schuck@nasa.gov
- HMI Pipeline Codes: in production, Intel Fortran with C-wrappers, and linked with Intel MKL math libraries with drop-in open source replacements (hopefully).

Planned Improvements

- More verification tests on other MHD codes
- Incorporate Doppler velocities to constrain vertical flows
- Incorporate HMI covariance matrices
- Consider spherical geometry

Démoulin, P., & Berger, M. A. 2003, Sol. Phys., 215, 203

Schuck, P. W. 2008, ApJ, 683, 1134,

<http://arxiv.org/abs/0803.3472>

Welsch, B. T., Abbett, W. P., DeRosa, M. L., Fisher, G. H., Georgoulis, M. K., Kusano, K., Longcope, D. W., Ravindra, B., & Schuck, P. W. 2007, ApJ, 670, 1434